# Incomparable Degrees in PACi and PAC Learning

# Gihanee Senadheera

senadheerad @winthrop.edu



Department of Mathematics Winthrop University

New England Recursion and Definability Seminar 2023 Wellesley College

October 14, 2023

イロト イ団ト イヨト イヨ

- ▶ PAC stands for **P**robably **A**pproximately **C**orrect
- It is a Machine learning model.
- It was introduced by Leslie Valiant in 1984.

・ロト ・日下・ ・ ヨト・

- PAC and PACi reducibilities give partial ordering and a degree structure.
- ▶ Helps to understand the structure of PAC learnability.
- ▶ If it is a linear ordering, then it has only one way of non-learnability.
- If incomparable degrees exist then there are at least two different ways of non-learnability.
- If there exists an embedding from known degrees to PACi or PAC degrees, then all the properties true for the known degree will be true for PACi or PAC degrees.

イロト イヨト イヨト

1. Let X be a set, called the *instance space*.

イロト イヨト イヨト イ

- 1. Let X be a set, called the *instance space*.
- 2. Let C be a subset of P(X) the power set of X, called a *concept class*.

Image: A matching of the second se

- 1. Let X be a set, called the *instance space*.
- 2. Let C be a subset of P(X) the power set of X, called a *concept class*.
- 3. The elements of *C* are called *concepts*.

Image: A matching of the second se

We say that *C* is *PAC Learnable* if and only if there is an algorithm *L* such that for every  $c \in C$ , every  $\epsilon, \delta \in (0, \frac{1}{2})$  and every probability distribution  $\mathfrak{D}$  on *X*, the algorithm *L* behaves as follows:

• • • • • • • • • • •

We say that *C* is *PAC Learnable* if and only if there is an algorithm *L* such that for every  $c \in C$ , every  $\epsilon, \delta \in (0, \frac{1}{2})$  and every probability distribution  $\mathfrak{D}$  on *X*, the algorithm *L* behaves as follows:

On input  $(\epsilon, \delta)$ , the algorithm *L* will ask for some number *n* of examples, and will be given  $\{(x_1, i_1), ..., (x_n, i_n)\}$  where  $x_k$  are independently randomly drawn from  $\mathfrak{D}$  and  $i_k = \chi_c(x_k)$ .

イロト イボト イヨト イヨ

We say that *C* is *PAC Learnable* if and only if there is an algorithm *L* such that for every  $c \in C$ , every  $\epsilon, \delta \in (0, \frac{1}{2})$  and every probability distribution  $\mathfrak{D}$  on *X*, the algorithm *L* behaves as follows:

On input  $(\epsilon, \delta)$ , the algorithm *L* will ask for some number *n* of examples, and will be given  $\{(x_1, i_1), ..., (x_n, i_n)\}$  where  $x_k$  are independently randomly drawn from  $\mathfrak{D}$  and  $i_k = \chi_c(x_k)$ .

The algorithm will then output some  $h \in C$  with probability at least  $1 - \delta$  in  $\mathfrak{D}$ , the symmetric difference of h and c has the probability at most  $\epsilon$  in  $\mathfrak{D}$ .

イロト イヨト イヨト

イロト イヨト イヨト イヨ

The set X is called the *instance space*, the set C is called the *concept* class and elements of C are called the *concepts*.

• • • • • • • • • • •

The set X is called the *instance space*, the set C is called the *concept* class and elements of C are called the *concepts*.

Given the inputs  $\epsilon, \delta \in (0, \frac{1}{2})$ 

• • • • • • • • • • •

The set X is called the *instance space*, the set C is called the *concept* class and elements of C are called the *concepts*.

Given the inputs  $\epsilon, \delta \in (0, \frac{1}{2})$ 

find m, large enough such that  $(1 - \epsilon)^m < \delta$  is satisfied.

The set X is called the *instance space*, the set C is called the *concept* class and elements of C are called the *concepts*.

Given the inputs  $\epsilon, \delta \in (0, \frac{1}{2})$ 

find *m*, large enough such that  $(1 - \epsilon)^m < \delta$  is satisfied.

Ask for *m* examples. Denoted as  $A = \{(x_1, i_1), ..., (x_m, i_m)\}$  where  $x_k$  are independently randomly drawn from  $\mathfrak{D}$  and  $i_k = \chi_c(x_k)$ .

The set X is called the *instance space*, the set C is called the *concept* class and elements of C are called the *concepts*.

Given the inputs  $\epsilon, \delta \in (0, \frac{1}{2})$ 

find m, large enough such that  $(1 - \epsilon)^m < \delta$  is satisfied.

Ask for *m* examples. Denoted as  $A = \{(x_1, i_1), ..., (x_m, i_m)\}$  where  $x_k$  are independently randomly drawn from  $\mathfrak{D}$  and  $i_k = \chi_c(x_k)$ .

Define  $B = \{x_k | (x_k, i_k) \in A \text{ and } i_k = 1\}$ . Define h = inf B.

イロト イヨト イヨト

The set X is called the *instance space*, the set C is called the *concept* class and elements of C are called the *concepts*.

Given the inputs  $\epsilon, \delta \in (0, \frac{1}{2})$ 

find *m*, large enough such that  $(1 - \epsilon)^m < \delta$  is satisfied.

Ask for *m* examples. Denoted as  $A = \{(x_1, i_1), ..., (x_m, i_m)\}$  where  $x_k$  are independently randomly drawn from  $\mathfrak{D}$  and  $i_k = \chi_c(x_k)$ .

Define  $B = \{x_k | (x_k, i_k) \in A \text{ and } i_k = 1\}$ . Define h = inf B.

Return the hypothesis  $H = (h, \infty)$ .

イロト イヨト イヨト

イロト イヨト イヨト イヨ

Suppose the target is  $(t,\infty)$ .

・ロト ・日 ・ ・ ヨト ・

Suppose the target is  $(t,\infty)$ .

Notice that  $t \leq h$ . Otherwise, our training data is wrong.



Figure 1: Training data error

(日) (四) (日) (日) (日)

Suppose the target is  $(t,\infty)$ .

Notice that  $t \leq h$ . Otherwise, our training data is wrong.

Suppose the target is  $(t,\infty)$ .

Notice that  $t \leq h$ . Otherwise, our training data is wrong.

Then  $(t,\infty) \triangle (h,\infty) = (t,h)$ .

Suppose the target is  $(t,\infty)$ .

Notice that  $t \leq h$ . Otherwise, our training data is wrong.

Then  $(t,\infty) \triangle (h,\infty) = (t,h)$ .

Define b such that  $\mathfrak{D}(t, b) < \epsilon$ .

• • • • • • • • • • •

Suppose the target is  $(t,\infty)$ .

Notice that  $t \leq h$ . Otherwise, our training data is wrong.

Then 
$$(t,\infty) \triangle (h,\infty) = (t,h)$$
.

Define b such that  $\mathfrak{D}(t, b) < \epsilon$ .

We can show that probability of h < b is less than  $\delta$ .

Image: A matching of the second se

Suppose the target is  $(t,\infty)$ .

Notice that  $t \leq h$ . Otherwise, our training data is wrong.

Then 
$$(t,\infty) \triangle (h,\infty) = (t,h)$$
.

Define b such that  $\mathfrak{D}(t, b) < \epsilon$ .

We can show that probability of h < b is less than  $\delta$ .

This probability is bounded by  $(1 - \epsilon)^m$  and  $(1 - \epsilon)^m < \delta$ .

• • • • • • • • • • •

Suppose the target is  $(t,\infty)$ .

Notice that  $t \leq h$ . Otherwise, our training data is wrong.

Then 
$$(t,\infty) \triangle (h,\infty) = (t,h)$$
.

Define b such that  $\mathfrak{D}(t, b) < \epsilon$ .

We can show that probability of h < b is less than  $\delta$ .

This probability is bounded by  $(1 - \epsilon)^m$  and  $(1 - \epsilon)^m < \delta$ . Since one example missing (t, b) has the probability  $(1 - \epsilon)$ .

Then m examples missing (t, b) has the probability  $(1 - \epsilon)^m$ .

イロト イヨト イヨト

#### Example

Suppose X is the real line.

- ▶ Let *C* be the set of positive half lines then *C* is PAC learnable.
- ▶ Let *C* be the set of negative half lines then *C* is PAC learnable.
- ▶ Let *C* be the set of intervals then *C* is PAC learnable.

Suppose *X* is  $\mathbb{R}^2$ .

- Let C be the set of axis aligned rectangles then C is PAC learnable.
- ▶ Let *C* be the set of convex *d*-gons then *C* is PAC learnable for any *d*.

Suppose  $X = \mathbb{R}^d$ .

▶ Let *C* be the set of linear-half spaces. Then *C* is PAC learnable.

A weakly effective concept class is a computable enumeration  $\varphi_e : \mathbb{N} \to \mathbb{N}$  such that  $\varphi_e(n)$  is a  $\Pi_1^0$  index for a  $\Pi_1^0$  tree  $T_{e,n}$ .

Image: A matching of the second se

An effective concept class is a weakly effective concept class  $\varphi_e(n)$  such that for each *n*, the set  $c_n$  of paths through  $T_{e,n}$  is computable in the sense that there is a computable function  $f_{c_n}(\sigma, r) : 2^{<\omega} \times \mathbb{Q} \to \{0, 1\}$  such that

$$F_{c_n}(\sigma, r) = \begin{cases} 1 & \text{if } B_r(\sigma) \cap c_n \neq \emptyset \\ 0 & \text{if } B_{2r}(\sigma) \cap c_n = \emptyset \\ 0 \text{ or } 1 & \text{otherwise} \end{cases}$$

where  $B_r(\sigma)$  is the set of all paths that either extend  $\sigma$  or first differ from it at the  $-\lceil lg(r) \rceil$  place or later.

(日) (四) (日) (日) (日)





Figure 2: Computable function  $f_{c_n}(\sigma, r)$ 

Gihanee Senadheera

Incomparable Degrees in PACi and PAC Learning

▶ **4 ≣** ▶ **≡ 9 9 0** October 14, 2023 12 / 44

イロト イヨト イヨト イヨト

An effective concept class is a weakly effective concept class  $\varphi_e(n)$  such that for each *n*, the set  $c_n$  of paths through  $T_{e,n}$  is computable in the sense that there is a computable function  $f_{c_n}(\sigma, r) : 2^{<\omega} \times \mathbb{Q} \to \{0, 1\}$  such that

$$f_{c_n}(\sigma, r) = \begin{cases} 1 & \text{if } B_r(\sigma) \cap c_n \neq \emptyset \\ 0 & \text{if } B_{2r}(\sigma) \cap c_n = \emptyset \\ 0 \text{ or } 1 & \text{otherwise} \end{cases}$$

where  $B_r(\sigma)$  is the set of all paths that either extend  $\sigma$  or first differ from it at the  $-\lceil lg(r) \rceil$  place or later.

We can say that an effective concept class is a set of  $\Pi_1^0$  classes. A  $\Pi_1^0$  class is expressed as the set of infinite paths through a computable tree or the set of infinite paths through a  $\Pi_1^0$  tree.

イロト イヨト イヨト

## Example

The class *C* of linear half-spaces in  $\mathbb{R}^d$  bounded by hyper-planes with computable coefficients is an effective concept class.

イロト イヨト イヨト イヨ

#### Example

The class *C* of linear half-spaces in  $\mathbb{R}^d$  bounded by hyper-planes with computable coefficients is an effective concept class.

Since the distance of a point from the boundary can be computed, the linear half-spaces with computable coefficients is a computable set.

Consider  $\mathbb{R}^2$ . There are algorithms to compute the distance from a point to a line. The line has computable coefficients. Here no need to use the full precision reals.

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PACi reduces to D, which we denote by  $C \leq_{PACi} D$ exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PACi reduces to D, which we denote by  $C \leq_{PACi} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that 1. g is a Turing functional

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PACi reduces to D, which we denote by  $C \leq_{PACi} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

- 1. g is a Turing functional
- 2. h is a computable function on indices

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PACi reduces to D, which we denote by  $C \leq_{PACi} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

- 1. g is a Turing functional
- 2. h is a computable function on indices
- 3. for all  $x \in X$  and for all  $c \in C$ , we have  $x \in c$  if and only if  $g(x) \in h(c)$ .
Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PACi reduces to D, which we denote by  $C \leq_{PACi} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

- 1. g is a Turing functional
- 2. h is a computable function on indices
- 3. for all  $x \in X$  and for all  $c \in C$ , we have  $x \in c$  if and only if  $g(x) \in h(c)$ .

The "i" indicates the independence of this definition from size and computation time.

< □ > < 同 > < 回 > < 回 >

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PAC reduces to D, denoted  $C \leq_{PAC} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PAC reduces to D, denoted  $C \leq_{PAC} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

1. g is a Turing functional and computable in polynomial time,

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PAC reduces to D, denoted  $C \leq_{PAC} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

- 1. g is a Turing functional and computable in polynomial time,
- 2. for all  $x \in X$  and for all  $c \in C$ , we have  $x \in c$  if and only if  $g(x) \in h(c)$

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PAC reduces to D, denoted  $C \leq_{PAC} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

- 1. g is a Turing functional and computable in polynomial time,
- 2. for all  $x \in X$  and for all  $c \in C$ , we have  $x \in c$  if and only if  $g(x) \in h(c)$
- 3. There is a polynomial p such that for any  $x \in X$  of size n, the element g(x) is of size at most p(n), and

< □ > < 同 > < 回 > < 回 >

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PAC reduces to D, denoted  $C \leq_{PAC} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

- 1. g is a Turing functional and computable in polynomial time,
- 2. for all  $x \in X$  and for all  $c \in C$ , we have  $x \in c$  if and only if  $g(x) \in h(c)$
- 3. There is a polynomial p such that for any  $x \in X$  of size n, the element g(x) is of size at most p(n), and
- 4. There is a polynomial q such that for every  $c \in C$  of size n, the concept h(c) is of size at most q(n).

イロト イヨト イヨト

Let C and D be concept classes. Then if C PAC-reduces to D, and D is PAC learnable, C is PAC learnable.

Let C and D be concept classes. Then if C PAC-reduces to D, and D is PAC learnable, C is PAC learnable.

# Proof:

Let L' be the learning algorithm for D. We use L' to learn C.

Let C and D be concept classes. Then if C PAC-reduces to D, and D is PAC learnable, C is PAC learnable.

#### Proof:

Let L' be the learning algorithm for D.

We use L' to learn C.

For a random example (x, c) of the unknown target concept  $c \in C$ , we can compute the labeled example (g(x), h(c)) and give it to L'.

Let C and D be concept classes. Then if C PAC-reduces to D, and D is PAC learnable, C is PAC learnable.

#### Proof:

Let L' be the learning algorithm for D.

We use L' to learn C.

For a random example (x, c) of the unknown target concept  $c \in C$ , we can compute the labeled example (g(x), h(c)) and give it to L'. If the instance  $x \in X$  are drawn according to  $\mathfrak{D}$ , then the instances  $g(x) \in Y$  are drawn according to some induced distribution  $\mathfrak{D}'$ .

Although we do not know the target concept c, our definition of reduction guarantees that the computed examples (g(x), h(c)) are consistent with some  $d \in D$ , and thus L' will output a hypothesis t' that has an error at most  $\epsilon$  with respect to  $\mathfrak{D}'$ .

Although we do not know the target concept c, our definition of reduction guarantees that the computed examples (g(x), h(c)) are consistent with some  $d \in D$ , and thus L' will output a hypothesis t' that has an error at most  $\epsilon$  with respect to  $\mathfrak{D}'$ .

Our hypothesis for c becomes t(x) = t'(g(x)), which has at most  $\epsilon$  error with respect to  $\mathfrak{D}$ .

< □ > < 同 > < 回 > < 回 >

As the size of the effective concept class, we can use the Kolmogorov complexity.

As the size of the effective concept class, we can use the Kolmogorov complexity.

The quantification of the amount of absolute information in individual objects that are invariant up to an additive constant is known as the Kolmogorov Complexity.

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros.

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros.

In this sequence, each of these trees  $c_n$  consists of a single infinite path. Let C be the concept class consisting of the above sequence of trees.

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros.

In this sequence, each of these trees  $c_n$  consists of a single infinite path. Let C be the concept class consisting of the above sequence of trees. Since  $c_n$  has only a single infinite path, identify each tree  $c_n$  by this single path.

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros.

In this sequence, each of these trees  $c_n$  consists of a single infinite path. Let C be the concept class consisting of the above sequence of trees. Since  $c_n$  has only a single infinite path, identify each tree  $c_n$  by this single path.

We calculate the Kolmogorov Complexity of the initial segment of the path of the tree  $c_n$ .

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros.

In this sequence, each of these trees  $c_n$  consists of a single infinite path. Let C be the concept class consisting of the above sequence of trees. Since  $c_n$  has only a single infinite path, identify each tree  $c_n$  by this single path.

We calculate the Kolmogorov Complexity of the initial segment of the path of the tree  $c_n$ .

Thus size of  $c_n$  is given by  $size(c_n) = K((c_n)_{1:n}|n) \le k$  where k is a constant. This is possible since the finite segment of the tree is computable.

イロト イヨト イヨト

Observe that the empty concept class on the empty instance space is reducible to any other concept class.

・ロト ・日 ・ ・ ヨト ・

Let C be an effective concept class over the instance space X and D an effective concept class over the instance space Y.

We say that C PAC reduces to D, denoted  $C \leq_{PAC} D$  exactly when there are functions  $g: X \to Y$  and  $h: C \to D$  such that

- 1. g is a Turing functional and computable in polynomial time,
- 2. for all  $x \in X$  and for all  $c \in C$ , we have  $x \in c$  if and only if  $g(x) \in h(c)$
- 3. There is a polynomial p such that for any  $x \in X$  of size n, the element g(x) is of size at most p(n), and
- 4. There is a polynomial q such that for every  $c \in C$  of size n, the concept h(c) is of size at most q(n).

イロト イヨト イヨト

- Observe that the empty concept class on the empty instance space is reducible to any other concept class.
- Also any concept class is reducible to itself through the identity function.

- Observe that the empty concept class on the empty instance space is reducible to any other concept class.
- Also any concept class is reducible to itself through the identity function.
- ► We can infer that there are ≤<sub>PAC</sub> incomparable concept classes since there are continuum many concept classes on a countably infinite instance space.

- Observe that the empty concept class on the empty instance space is reducible to any other concept class.
- Also any concept class is reducible to itself through the identity function.
- ► We can infer that there are ≤<sub>PAC</sub> incomparable concept classes since there are continuum many concept classes on a countably infinite instance space.
- This degree structure is analogous to Turing degrees and their structures. So, we can expect the effective concept classes to behave in a similar manner to computably enumerable degrees.

イロト イヨト イヨト

We say  $C \sim_{PACi} D$  if  $C \leq_{PAC_i} D$  and  $D \leq_{PAC_i} C$ , the relation  $\sim$  is an equivalence relation. The PACi degree of concept class C is  $deg(C) = \{D : D \sim_{PACi} C\}$ 

< □ > < 同 > < 回 > < 回 >

We say  $C \sim_{PACi} D$  if  $C \leq_{PAC_i} D$  and  $D \leq_{PAC_i} C$ , the relation  $\sim$  is an equivalence relation. The PACi degree of concept class C is  $deg(C) = \{D : D \sim_{PACi} C\}$ 

#### Definition

We say  $C \sim_{PAC} D$  if  $C \leq_{PAC} D$  and  $D \leq_{PAC} C$ , the relation  $\sim$  is an equivalence relation. The PAC degree of concept class C is  $deg(C) = \{D : D \sim_{PAC} C\}$ 

< □ > < 同 > < 回 > < 回 >

# Example

Let  $X = X' = \mathbb{R}$  be the two instance spaces.

Let C be the set of positive half lines and C' be the set of negative half lines.

# Example

Let  $X = X' = \mathbb{R}$  be the two instance spaces.

Let C be the set of positive half lines and C' be the set of negative half lines.

The positive half lines are bounded below. If positive half lines are bounded below by a computable lower bound then the concept class C is an effective concept class.

Let  $X = X' = \mathbb{R}$  be the two instance spaces.

Let C be the set of positive half lines and C' be the set of negative half lines.

The positive half lines are bounded below. If positive half lines are bounded below by a computable lower bound then the concept class C is an effective concept class.

Similarly we can show that C' is also an effective concept class.

Let  $X = X' = \mathbb{R}$  be the two instance spaces.

Let C be the set of positive half lines and C' be the set of negative half lines.

The positive half lines are bounded below. If positive half lines are bounded below by a computable lower bound then the concept class C is an effective concept class.

Similarly we can show that C' is also an effective concept class.

Define  $g : \mathbb{R} \to \mathbb{R}$  by g(x) = -x and  $h : C \to C'$  by  $h((a, \infty)) = (-\infty, -a)$ .

< □ > < 同 > < 回 > < 回 >

Let  $X = X' = \mathbb{R}$  be the two instance spaces.

Let C be the set of positive half lines and C' be the set of negative half lines.

The positive half lines are bounded below. If positive half lines are bounded below by a computable lower bound then the concept class C is an effective concept class.

Similarly we can show that C' is also an effective concept class.

Define  $g : \mathbb{R} \to \mathbb{R}$  by g(x) = -x and  $h : C \to C'$  by  $h((a, \infty)) = (-\infty, -a)$ .

Now we can show that for all  $x \in \mathbb{R}$  and for all positive half lines  $c = (a, \infty)$  in C we have  $x \in c$  iff  $g(x) \in h(c)$  where h(c) is a negative half line.

イロト イヨト イヨト

Let  $X = X' = \mathbb{R}$  be the two instance spaces.

Let C be the set of positive half lines and C' be the set of negative half lines.

The positive half lines are bounded below. If positive half lines are bounded below by a computable lower bound then the concept class C is an effective concept class.

Similarly we can show that C' is also an effective concept class.

Define  $g : \mathbb{R} \to \mathbb{R}$  by g(x) = -x and  $h : C \to C'$  by  $h((a, \infty)) = (-\infty, -a)$ .

Now we can show that for all  $x \in \mathbb{R}$  and for all positive half lines  $c = (a, \infty)$  in C we have  $x \in c$  iff  $g(x) \in h(c)$  where h(c) is a negative half line.

This will give us  $C \leq_{PACi} C'$ . With appropriate functionals, we can show that  $C' \leq_{PACi} C$ . Thus  $C \sim C'$ .

イロト イヨト イヨト

There exist effective concept classes C and D over the instance space  $X = Y = 2^{\omega}$  such that C does not PACi reduce to D and also D does not PACi reduce to C. (i.e.  $C \leq_{PACi} D$  and  $D \leq_{PACi} C$ ).

• • • • • • • • • • •

The two concept classes C and D are constructed over the instance spaces X and Y respectively. Let  $\{h_t | t \in \mathbb{N}\}$  enumerate the set of all partial computable functions from  $\mathbb{N} \to \mathbb{N}$ .

< □ > < 同 > < 回 > < 回 >

Consider  $R_{2t}$ .

To satisfy the requirement  $R_{2t}$  we will attach a potential witness c: a concept, to  $R_{2t}$  which is not yet enumerated in C.

We choose c such that c is an index for a tree.

• • • • • • • • • • • •

Consider  $R_{2t}$ .

To satisfy the requirement  $R_{2t}$  we will attach a potential witness c: a concept, to  $R_{2t}$  which is not yet enumerated in C.

We choose c such that c is an index for a tree.

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros. In this sequence each of these trees  $c_n$ , consists of a single infinite path.
We will use  $B_s$  to keep track of the set of all trees that we plan not to enumerate in C.

We will use  $A_s$  to keep track of the set of all trees that we plan not to enumerate in D.

We will use  $B_s$  to keep track of the set of all trees that we plan not to enumerate in C.

We will use  $A_s$  to keep track of the set of all trees that we plan not to enumerate in D.

At stage s pick a c such that  $c \notin B_s$  and  $c \notin C_s$  and  $h_t(c) \notin D_s$ .

We will use  $B_s$  to keep track of the set of all trees that we plan not to enumerate in C.

We will use  $A_s$  to keep track of the set of all trees that we plan not to enumerate in D.

At stage s pick a c such that  $c \notin B_s$  and  $c \notin C_s$  and  $h_t(c) \notin D_s$ .

We will enumerate c in  $C_s$  and enumerate  $h_t(c)$  in  $A_s$ .

Thus we restrain the tree  $h_t(c)$  from later entering to D by checking the condition,  $d \notin A_{s+1}$ , and selecting the next indexed concept from the sequence.

イロト イヨト イヨト

We have  $C \not\leq_{PAC_i} D$ .

イロト イヨト イヨト イヨ

We have  $C \not\leq_{PAC_i} D$ .

The strategy for  $R_{2t+1}$  is the same but with roles of  $C_s$  and  $D_s$  reversed.

イロト イヨト イヨト イヨ

We have  $C \not\leq_{PAC_i} D$ .

The strategy for  $R_{2t+1}$  is the same but with roles of  $C_s$  and  $D_s$  reversed.

We call the sets A and B restraint sets.

• • • • • • • • • • • •

Let  $X = Y = 2^{\omega}$ .

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros. In this sequence each of these trees  $c_n$ , consists of a single infinite path.

Let  $X = Y = 2^{\omega}$ .

Let  $\{c_n\}_{n=1}^{\infty}$  be a family of trees, where  $c_n$  has n number of 1's and followed by zeros. In this sequence each of these trees  $c_n$ , consists of a single infinite path.

**Stage** s = 0: Let  $C_0 = D_0 = \phi$  and  $A_0 = B_0 = \phi$ .

**Stage** *s* + 1 :

Requirement  $R_{2t}$  requires attention, if we have not enumerated a witness,  $c \in C$  for the requirement  $R_{2t}$ .

Requirement  $R_{2t+1}$  requires attention, if we have not enumerated a witness,  $d \in D$  for the requirement  $R_{2t+1}$ .

イロト イヨト イヨト

**Suppose** i = 2t. Now  $R_{2t}$  receives attention.

イロト イヨト イヨト イ

**Suppose** i = 2t. Now  $R_{2t}$  receives attention.

Pick a tree c from the family  $\{c_n\}$  defined above with  $c = c_n$  for some n < s such that  $c \notin C_s$  and  $c \notin B_s$  and  $h_t(c) \notin D_s$ .

**Suppose** i = 2t. Now  $R_{2t}$  receives attention.

Pick a tree c from the family  $\{c_n\}$  defined above with  $c = c_n$  for some n < s such that  $c \notin C_s$  and  $c \notin B_s$  and  $h_t(c) \notin D_s$ .

If such a *c* exists enumerate  $c \in C_{s+1}$  and  $h_t(c)$  in  $A_{s+1}$ . If such a *c* does not exist then do nothing.

< □ > < 同 > < 回 > < 回 >

**Suppose** i = 2t. Now  $R_{2t}$  receives attention.

Pick a tree c from the family  $\{c_n\}$  defined above with  $c = c_n$  for some n < s such that  $c \notin C_s$  and  $c \notin B_s$  and  $h_t(c) \notin D_s$ .

If such a *c* exists enumerate  $c \in C_{s+1}$  and  $h_t(c)$  in  $A_{s+1}$ . If such a *c* does not exist then do nothing.

**Suppose** i = 2t + 1. Now  $R_{2t+1}$  receives attention.

(日) (同) (日) (日)

**Suppose** i = 2t. Now  $R_{2t}$  receives attention.

Pick a tree c from the family  $\{c_n\}$  defined above with  $c = c_n$  for some n < s such that  $c \notin C_s$  and  $c \notin B_s$  and  $h_t(c) \notin D_s$ .

If such a *c* exists enumerate  $c \in C_{s+1}$  and  $h_t(c)$  in  $A_{s+1}$ . If such a *c* does not exist then do nothing.

**Suppose** i = 2t + 1. Now  $R_{2t+1}$  receives attention.

Pick a tree d from the family  $\{c_n\}$  with  $d = c_n$  for some n < s such that  $d \notin D_s$  and  $d \notin A_s$  and  $h_t(d) \notin C_s$ .

(日) (四) (日) (日) (日)

**Suppose** i = 2t. Now  $R_{2t}$  receives attention.

Pick a tree c from the family  $\{c_n\}$  defined above with  $c = c_n$  for some n < s such that  $c \notin C_s$  and  $c \notin B_s$  and  $h_t(c) \notin D_s$ .

If such a c exists enumerate  $c \in C_{s+1}$  and  $h_t(c)$  in  $A_{s+1}$ . If such a c does not exist then do nothing.

**Suppose** i = 2t + 1. Now  $R_{2t+1}$  receives attention.

Pick a tree d from the family  $\{c_n\}$  with  $d = c_n$  for some n < s such that  $d \notin D_s$  and  $d \notin A_s$  and  $h_t(d) \notin C_s$ .

If d exists then enumerate  $d \in D_{s+1}$  and  $h_t(d)$  in  $B_{s+1}$ . Do nothing if such a d does not exist.

イロト イヨト イヨト

At each stage, we will be checking through a finite amount of trees in  $C_s$ ,  $D_s$ ,  $A_s$ , or  $B_s$ .

When a requirement is satisfied at stage s it will remain satisfied forever. Thus we have  $C \nleq_{PAC_i} D$  and  $D \nleq_{PAC_i} C$ 

#### Theorem

There exist effective concept classes C and D over the instance space  $X = Y = 2^{\omega}$  such that C does not PAC reduce to D and also D does not PAC reduce to C. (i.e.  $C \nleq_{PAC} D$  and  $D \nleq_{PAC} C$ ).

• • • • • • • • • • •

Requirements :

 $R_{2t}$ : there exists  $\sigma \in c$  where  $c \in C$  s.t.  $g_t(\sigma) \notin d, \forall d \in D$ 

 $R_{2t+1}$  : there exists  $au \in d$  where  $d \in D$  s.t.  $g_t( au) \notin c, orall \ c \in C$ 

Image: A math the second se

We can define a jump for the effective concept classes also.

イロト イヨト イヨト イヨ

We can define a jump for the effective concept classes also.

We can show that  $deg(A \oplus B)$  is the least upper bound for the deg(A) and deg(B) in (P, <) where P is the class of all PAC degrees. The degree P forms a partially ordered set under relation  $deg(A) \leq deg(B)$ .

We can define a jump for the effective concept classes also.

We can show that  $deg(A \oplus B)$  is the least upper bound for the deg(A) and deg(B) in (P, <) where P is the class of all PAC degrees. The degree P forms a partially ordered set under relation  $deg(A) \leq deg(B)$ .

We can show that  $\bigoplus_{i \in \omega} C_i$  is an effective concept class.

$$(\oplus_{i\in\omega}C_i)_e = \{1^i 0\sigma \mid \sigma \in (C_i)_e, i, e \in \omega\}$$

< □ > < 同 > < 回 > < 回 >

e-th tree



## Figure 3: The e-th tree of the concept class $\bigoplus_{i \in \omega} C_i$

イロト イヨト イヨト イヨ

## A Greatest Effective Concept Class

Theorem  $\bigoplus_{i \in \omega} C_i \text{ is an effective concept class.}$ 

イロト イヨト イヨト イヨ

#### Theorem

 $\bigoplus_{i\in\omega} C_i \text{ is an effective concept class.}$ 

Proof:

Since each effective concept class,  $C_i$  is computable, there exist a computable  $f_{c_n}^i(\sigma, r)$  for each *i*. Then define  $f_{c_n}(\sigma, r): 2^{<\omega} \times \mathbb{Q} \to \{0, 1\}$ 

$$f_{c_n}(\sigma, r) = \begin{cases} 1 & \text{if } \sigma = 1^{|\sigma|} \\ f_{c_n}^i(\tau, r') & \text{if } \sigma = 1^i 0\tau \end{cases}$$

## A Greatest Effective Concept Class

# Theorem $deg\left(\bigoplus_{j\in\omega}A_j\right)$ is the least upper bound for $\{deg(A_y)|y\in\omega\}$ .

イロト イ団ト イヨト イヨト

### A Greatest Effective Concept Class

Theorem  $deg\left(\bigoplus_{j\in\omega}A_j\right)$  is the least upper bound for  $\{deg(A_y)|y\in\omega\}$ . Proof:

$$g_{y}: 2^{\omega} \to 2^{\omega}$$
 and  $h_{y}: A_{y} \to \bigoplus_{j \in \omega} A_{j}$  by  
 $\sigma \mapsto 1^{y} 0 \sigma$  and  $(A_{y})_{e} \mapsto \left(\bigoplus_{j \in \omega} A_{j}\right)_{e}$  (1)

Hence  $A_y \leq_{PACi} \bigoplus_{j \in \omega} A_j$  for all y. Therefore  $deg(A_y) \leq deg\left(\bigoplus_{j \in \omega} A_j\right)$  for all y (2) Let  $\mathcal P$  be the PACi degrees of effective concept class. Let  $\mathcal C$  be the 1-degree of c.e. sets.

Is there  $\phi : \mathcal{C} \to \mathcal{P}$  such that  $\mathbf{a} \leq_1 \mathbf{b}$  iff  $\phi(\mathbf{a}) \leq_{PACi} \phi(\mathbf{b})$ ?

Let  $\mathcal P$  be the PACi degrees of effective concept class. Let  $\mathcal C$  be the 1-degree of c.e. sets.

Is there  $\phi : \mathcal{C} \to \mathcal{P}$  such that  $\mathbf{a} \leq_1 \mathbf{b}$  iff  $\phi(\mathbf{a}) \leq_{PACi} \phi(\mathbf{b})$ ?

Sketch of the proof:

There are c.e. sets  $W_{e_1} \in \mathbf{a}$  and  $W_{e_2} \in \mathbf{b}$ .

(日)

Let  $\mathcal P$  be the PACi degrees of effective concept class. Let  $\mathcal C$  be the 1-degree of c.e. sets.

Is there  $\phi : \mathcal{C} \to \mathcal{P}$  such that  $\mathbf{a} \leq_1 \mathbf{b}$  iff  $\phi(\mathbf{a}) \leq_{PACi} \phi(\mathbf{b})$ ?

Sketch of the proof:

There are c.e. sets 
$$W_{e_1} \in \mathbf{a}$$
 and  $W_{e_2} \in \mathbf{b}$ .  
 $W_{e_1} \mapsto \{c_n | n \in W_{e_1}\} = C_{\phi(e_1)}$  where  $c_n = 1^n \overline{0}$ .  
 $W_{e_2} \mapsto \{c_n | n \in W_{e_2}\} = C_{\phi(e_2)}$ .

(日)

Since  $W_{e_1} \leq_1 W_{e_2}$  there is a 1-1 function  $\psi$ .

$$\psi: W_{e_1} \longrightarrow W_{e_2}$$

$$n \longrightarrow \psi(n)$$

$$\phi \downarrow \qquad \qquad \qquad \downarrow \phi$$

$$c_n \longrightarrow c_{\psi(n)}$$
(3)

イロト イヨト イヨト イヨ

Since  $W_{e_1} \leq_1 W_{e_2}$  there is a 1-1 function  $\psi$ .

< □ > < □ > < □ > < □ > < □ >

#### Lemma

If  $W_{e_1} \not\leq_1 W_{e_2}$  then  $C_{\phi(e_1)} \not\leq_{PACi} C_{\phi(e_2)}$ .

Sketch of the proof:

we will use the contrapositive of this statement. That is, if  $C_{\phi(e_1)} \leq_{PACi} C_{\phi(e_2)}$  then  $W_{e_1} \leq_1 W_{e_2}$ . Since  $C_{e_1} \leq_{PACi} C_{e_2}$  there exist g and h but we will consider only h.



(日) (四) (日) (日) (日)

To obtain the 1-reduction between  $W_{\phi'(e_1)}$  and  $W_{\phi'(e_2)}$  define  $\psi$  as follows. Each  $n \in W_{\phi'(e_1)}$  will be mapped to h(n) as in Equation 6.

$$\psi: W_{\phi'(e_1)} \to W_{\phi'(e_2)}$$

$$n \longmapsto h(n)$$
(6)

• • • • • • • • • • •

## Thank you!

Gihanee Senadheera

Incomparable Degrees in PACi and PAC Learning

▶ **4 ≣ ▶ ≡ • ○ Q ○** October 14, 2023 **44** / **44** 

・ロト ・ 日 ト ・ 日 ト ・ 日